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Virtual Reality & Physically-Based Simulation Interaction Metaphors



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- First computer game (probably):
 - Spacewars, 1961, MIT
 - Two players, two spaceships ("wedge" and "needle"), each can fire torpedos
 - With it came the first real interaction devices and metaphors





A Classification of Interaction Tasks

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- Universal Interaction Tasks (UITs) in VEs [Bowman]:
 - 1. Navigation = change viewpoint
 - 2. Selection = define object or place for next task
 - 3. Manipulation = grasp, move, manipulate object
 - 4. System control = menus, widgets sliders, number entry, etc.
 - Model and modify geometry (very rare; not in Bowman's UITs)
- Basic interaction tasks (BITs) in 2D GUIs [Foley / vanDam]:
 - Selection (objects menus, ..)
 - Positioning (incl. orientation) or manipulation
 - Entering quantities (e.g., numbers)
 - Text input (via keyboard or speech input)

More Interaction Tasks

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- Search (e.g., searching a scene for a specific object)
- Ambient, implicit, playful, non-purposeful interaction
 - E.g., playing around with a virtual spraying can
- Sculpting / modeling surfaces
- Making an avatar dance by whole body interaction



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Digression: Classification of Widgets for 3D UIs

Direct 3D Object Interaction		
	Object Selection	
	Geometric Manipulation	
D-Scene Manipulation		
	Orientation and Navigation	
	Scene Presentation Control	
Exploration and Visualization		
	Geometric Exploration	
	Hierarchy Visualization	
	3D Graph Visualization	
	2D-Data and Document Visualization	
	Scientific Visualization	
System / Application Control		
	State Control / Discrete Valuators	
	Continuous Valuators	I
	Special Value Input	
	Menu Selection	
	Containers	

















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Interaction Metaphors

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The Design of User Interfaces



- There are two main approaches:
 - Natural interaction:
 - Try to resemble reality and the interaction with it as closely as possible
 - "Magic" interaction
 - Give the user new possibilities beyond reality
 - Challenge: keep the cognitive overhead as low as possible, so that users don't get distracted from their task!
- Tools:

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- Direct user action (e.g., motion of the body, gesture, head turning, ...)
 - Pro: well suited if intuitive; con: possibilities are somewhat limited
- Physical Devices (e.g., steering wheel, button, ...)
 - Pro: haptic feedback affords precise control
 - Con: not easy to find/devise novel & useful devices
- Virtual devices (e.g., menus, virtual sliders, ...)
 - Pro: very flexible, reconfigurable, "anything goes"
 - Con: can be difficult to use because of lack of force feedback



- Goals (in particular in VR):
 - 1. Intuitive / natural interaction (usability)
 - By definition: easy to learn
 - Adjust to the users expertise (expert vs. novice)
 - 2. Efficient interaction (user performance)
 - Precision, speed, productivity of the users
- Problems (especially in VR):
 - No physical constraints (interaction in mid-air)
 - In particular: no haptic feedback
 - Efficient interaction with objects outside of the user's reach
 - Noise / jitter / imprecision in tracking data
 - Fatigue
 - No standards

There has never been a high performance task done in the history of this planet, to the best of my knowledge, that has ever been done well with an intuitive interface. [Brian Ferran]

Gesture Recognition

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- Is basically a simple classification problem:
 - Given: a flex vector $x \in \mathbb{R}^n$, $n \approx 20$ = joint angles
 - Wanted: gesture $G(x) \in \{$ "Fist", "Hitch-hike", ... $\}$
- Wanted: an algorithm that is ...
 - .. user independent
 - .. robust (> 99%)
 - .. Fast

An Extremely Simple Gesture Recognition Algorithm



- Neural network is fine, if lots of gestures, or some of them are inside the parameter space
 - However, experience show: users can remember only a small set (e.g. 5)
- In the following: only few gestures at the border of parameter space
 - Discretize flex vector

 $f \in [0,1]^d
ightarrow f' \in \{-1,0,+1\}^d$

0 = flex is "somewhere in the middle"

- Gesture = region of d-dimensional parameter cube
- Represent each region/gesture by a discrete vector:

$$g \in \{-1,0,+1\}^d$$
 $0 = don't$ care

• Gesture *i* is recognized iff

$$f' \cdot g_i = |g_i|$$

Condition for this to work: regions of different gestures must not overlap



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- Implementation details:
 - Do automatic calibration at runtime to fill the range [0,1]:
 - Maintain a running min/max and map it to [0,1]
 - Over time, shrink min/max gradually (for robustness against outliers)
 - Ignore transitory gestures
- Dynamic gestures =
 - 1.Sequence of static gestures (e.g., sign language)
 - 2.Path of a finger / hand
 - Utility for VR?





- Comprises: Wayfinding & Locomotion
- Locomotion / Travel =
 - Cover a distance (in RL or in VR)
 - Maneuvering (= place viewpoint / viewing direction exactly)
- Wayfinding =
 - Strategy to find a specific place (in an unknown building / terrain)
 - Comprises: experience, cognitive skills, ...



How do People Solve a Wayfinding Task



- How do people find their *way*:
 - Natural hints/clues
 - Signs (man-made)
- A simple user model for way finding:



- In VEs, there can be 2 kinds of navigation [sic] aids:
 - Aids for improving the user's performance in the virtual environment
 - Aids that help increase the user's performance later in the real world (i.e., that increase the training effect)





- Question: do humans create a mental map of their environment in order to solve wayfinding tasks?
- Answer: probably yes, but not like a printed street map; rather like a non-planar graph that stores edge lengths



Kerstin Schill, Uni Bremen

Techniques for Navigation in VEs



- Real user navigation, e.g., walking, turning head, ...
- Point-and-fly (especially in Caves and HMDs)
- Scene-in-hand

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- World-in-Miniature
- Orbital mode
- And some more ...







Taxonomies are a way to explore (exhaustively, if possible) the *design space* of an interaction task!

An Abstract Representation of the User



- User = Head, Hand, perhaps whole body (avatar)
- The "flying carpet" metaphor :
 - User = camera

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root

- Camera is placed on a carpet / cart / wagon
- Representation as (part of) a scenengraph:



rest of



The Point-and-Fly Metaphor

Controlling sensors:

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- Head sensor \rightarrow viewpoint
- Hand sensor → moves cart:

$$M_C^t = M_C^{t-1} \cdot \operatorname{Transl}(s \cdot \mathbf{t})$$

root rest of the world cart M_C^t viewpoint hand

s = speed,

t = translation vector = 3rd column of hand tracking sesnor

- Generalization: use graphical objects instead of sensor to derive translation direction
- Specification of the speed:
 - Constant (e.g. with Boom)
 - Flexion of the thumb
 - Depending on distance |hand body|
 - Make it independent of framerate





Perception of the Distance Walked in VR



- Question: how can the sense of presence be increased while navigating in a VE? (using point-and-fly)
- Idea:
 - Make the viewpoint oscillate like in reality
 - (First-person-shooter games invented this earlier ;-))



Results:

- Only vertical oscillation helps increase presence
- Users prefer slight oscillation over no oscillation
- Short "travel distances" can be estimated more precisely (~ factor 2)

hand

The Scene-in-Hand / Eyeball-in-Hand Metaphor

- Scene-in-hand:
 - "Grabbing the air" technique
 - Cart remains stationary, scene gets rotated by hand sensor about a specific point in space
 - The transformation:

 $M_W^t = M_H^t \cdot (M_H^{t_0})^{-1} \cdot M_W^{t_0}$

• Eyeball-in-hand:

- Viewpoint is controlled directly by hand
- Can be absolute or relative (accumulating) mode



viewpoint





Two-Handed Navigation (with Pinch Gloves)

- Question: how to navigate with both hands? (increase input bandwidth)
- Idea: only use 2 points and 1-2 triggers (\rightarrow pinch gloves)
- Idea: use "scene-in-hand"
 - 1 trigger, 1 moving point \rightarrow translate the scene
 - 2 trigger, 1 fixed point , 1 moving point \rightarrow rotate the scene
 - 2 trigger, 2 Punkte bewegt \rightarrow scale the scene
- Not well-established in VR (probably because pinch gloves have not prevailed)
 - But: is the standard today on handhelds! ;-)
- Variation:
 - Direction = vector between both hands
 - Speed = length of vector



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Navigation Without Hands

- Idea: project a scaled down version of the VE on the floor (map) and use feet
- Coarse navigation: teleportation → user walks to the new place/viewpoint on the map and triggers teleportation
- System commands involved:
 - 1.Bring up map = look at floor + trigger
 - 2.Teleportation = look at floor + trigger
 - 3.Dismiss map = look up + trigger
 - Trigger = speech command or "foot gesture"
- Accurate navigation: "lean" towards desired direction; speed = e.g., leaning angle







Exploration of VEs using a Magic Mirror



- Task/goal: present a second viewpoint (like inset in an image) intuitively in a VE, and allow for its manipulation
- Idea: use the mirror as a metaphor \rightarrow "magic mirror"
 - One object serves as hand mirror (could even look like it)
 - Keeps a fixed position relative to camera (follows head motions)
 - Can be manipulated like any other object in the VE
- Additional features (not possible with real mirrors):
 - Zooming

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- Magnification / scaling down of image in mirror
- Clipping of objects in front of mirror (which occlude mirror)
- "Un-mirror" scene visible in mirror ("Richtig-herum-Drehen")
- Switch between main viewpoint and mirror viewpoint



- Examples:
- Implementation:
 - Render 2x
 - First, render only into a small viewport (in the shape of the mirror) with mirrored viewpoint
 - Save as texture
 - Second, render into complete viewport from main viewpoint
 - Third, render texture on top of mirror object (no z test)
- Or, use method presented in Computer Graphics class





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The Immersive Navidget

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- Metaphor for defining the viewpoint directly
- Input device: wand with wheels and buttons
- Decomposition of the task:
 - 1. Define center of the sphere
 - Will be the new center of interest (COI)
 - E.g. by ray casting: shoot ray into scene, intersection point = new COI
 - Define radius of sphere = distance of new viewpoint from COI
 - Here: specified using wheel on wand
 - 3. Define viewpoint on sphere (using ray)
 - Animate viewpoint on path towards new viewpoint (= smooth teleportation)
 - 5. Switch to next phase using a button











Navidget for Immersive Virtual Environments Sebastian Knödel, Martin Hachet iparla.labri.fr



- Goal: an intuitive metaphor for manipulating the parameters of perspective projections
- Observation: drawing experts construct perspective drawings by way of vanishing points
- Idea:
 - Manipulate the vanishing points
 - As metaphor use the edges of a (projected) cube
- By manipulating the "handles" afforded by the cube, we can modify parameters:
 - Orientation, zoom, pan, proj. center













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- Idea: if we had a model of how users "work", then we could predict how they will interact with a specific UI and what their user performance will be
- Advantage (theoretically): no user studies and no UI mock-ups necesary any more
- Related fields: psychophysics, user interface design, usability



The Power Law of Practice



Describes, what time is needed to perform an activity after the *n*-th repetition:

$$T_n = \frac{I_1}{n^a}$$

- T_1 = time needed for first performance of the activity,
- T_n = time for *n*-th repetition,
- $a \approx 0.2 \dots 0.6$
- Warning:
 - Applies only to mechnical activities, e.g. :
 - Using the mouse, typing on the keyboard
 - Does not apply to cognitive activities, e.g., learning for exams! ;-)
- This effect must be kept in mind when designing experiments!





Describes the time needed to make a 1-out-of-n selection, but there cannot be any cognitive workload involved:

$$T = I_c \log_2(n+1)$$
 , $I_c \approx 150$ msec

where *n* = number of choices

- Example: n buttons + n lights, one is lighted up randomly, user has to press corresponding button
- Assumption: the distribution of the choices is uniform!
- Warning: don't apply this law too blindly!
 - E.g., practice has a big influence on reaction time
- Sometimes, Hick's law is taken as proof that one large menu is more time-efficient than several small submenus ("rule of large menus") ... I argue this is mathematically correct only because of the "+1", for which there is no clear experimental evidence! Besides, there are many other factors involved in large menus (clarity, Fitts' law, ...)







- Describes the time needed to reach a target
- Task: reach and hit a specific target as quickly and as precisely as possible with your hand / pencil / mouse /etc., from a resting position → "target acquisition"
- The law:

$$T = b \log_2(\frac{D}{W} + 1) + a$$

where D = distance between resting position and target, W = diameter of the target

The "index of difficulty" (ID) =

$$\log_2(rac{D}{W}+1)$$



Demo / Experiment



 Fitt's Law does apply directly to mouse movements needed to hit icons and buttons



Marcin Wichary, Vrije Universiteit: http://fww.few.vu.nl/hci/interactive/fitts/



Applications of Fitts' Law



- "Rule of Target Size": The size of a button should be proportional to its expected frequency of use
- Other consequences:

"Macintosh fans like to point out that Fitts's Law implies a very large advantage for Mac-style edge-of-screen menus with no borders, because they effectively extend the depth of the target area off-screen. This prediction is verified by experiment." [Raymond & Landley: "The Art of Unix Usability", 2004]







- Tear-off menus and context menus: they decrease the average travel distance D
- Apple's "Dock": the size of the icons gets adjusted dynamically



- Obvious limitations of Fitts's Law:
 - Fitts's Law cannot capture all aspects/widgets of a GUI
 - E.g. moving target (like scrollable lists)
 - There are many other decisions with regards to the design of a UI that are contrary to an application of Fitts's law

Fun and intructive quiz: go to the homepage of this VR course \rightarrow scroll down to section "Online Literatur und Resources im Internet" \rightarrow find "A Quiz Designed to Give You Fitts"



Bad Examples

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Digression: the 80/20 Rule



- 80% all the total usage time of a product, we utilize only 20% of its features
 - Applies to menus, software as a whole, "consumer electronics", cars, ...
- 80% of the malfunctions of a product have their cause in only 20% of its components
- 80% all the old box in the software are caused by only 20% of its programmers and designers
- 80% all the revenue of the company is generated by only20% of their products

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